## 2. Linear Transformations

Let  $\mathcal{X}, \mathcal{Y}$  be Banach spaces. A mapping  $f : \mathcal{X} \to \mathcal{Y}$  is *linear* if it satisfies the following two properties:

- 1. f(x+y) = f(x) + f(y) for all  $x, y \in \mathcal{X}$
- 2.  $f(\alpha x) = \alpha f(x)$  for all  $x \in \mathcal{X}, \alpha \in \mathbf{R}$ .

A linear map  $f: \mathcal{X} \to \mathcal{Y}$  is called *bounded* if there is a constant C > 0 such that  $|f(x)| \leq C|x|$  for all  $x \in \mathcal{X}$ .

## Facts:

- 1. A linear map f is bounded if and only if it is continuous.
- 2. The linear map f is bounded if and only if the quantity  $\sup_{|x| \le 1} |f(x)|$  is finite.
- 3. The quantity  $\sup_{\mid x\mid \leq 1} \mid f(x)\mid$  in the preceding statement is also equal to  $\sup_{\mid x\mid = 1} \mid f(x)\mid$
- 4. Every linear map whose domain is  $\mathbf{R}^n$  or  $\mathbf{C}^n$  is bounded (hence continuous).

If f is a bounded linear map (transformation), we set  $|f| = \sup_{|x|=1} |f(x)|$ . This defines a norm in the space  $L(\mathcal{X}, \mathcal{Y})$  of bounded linear maps from  $\mathcal{X}$  to  $\mathcal{Y}$ , making it into a Banach space also.

## Fixed Point Theorems

Many existence theorems for differential equations can be reduced to fixed point theorems in appropriate function spaces. Here we will discuss a few relevant results.

Let X be a metric space and let  $T: X \to X$  be a mapping. A fixed point of T is a point  $x \in X$  such that T(x) = x.

A self-map T of a metric space  $\mathcal{X}$  is called a contraction (or contraction map or mapping) if there is a constant  $0 < \lambda < 1$  such that

$$d(Tx, Ty) \le \lambda d(x, y)$$

for all  $x, y \in \mathcal{X}$ . Thus,  $T : \mathcal{X} \to \mathcal{X}$  is a contraction if and only it is Lipschitz with Lipschitz constant less than 1.

**Theorem**. (Contraction Mapping Theorem) Suppose  $\mathcal{X}$  is a complete metric space and  $T: \mathcal{X} \to \mathcal{X}$  is a contraction map. Then, T has a unique fixed point  $\bar{x}$  in  $\mathcal{X}$ . Moreover, if x is any point in  $\mathcal{F}$ , then the sequence of iterates  $x, Tx, T^2x, \ldots$  converges to  $\bar{x}$  exponentially fast.

## Proof.

Uniqueness:

If  $0 < \lambda < 1$  is the contraction constant for T and Tx = x, Ty = y, then

$$d(x,y) = d(Tx,Ty) \le \lambda d(x,y)$$

which implies that d(x, y) = 0. This in turn implies that x = y. QED. Existence:

Let  $x_0 = x, x_1 = Tx, x_i = T^i x, ...$ 

Then.

 $d(x_{n+1},x_n) \leq \lambda d(x_n,x_{n-1}) \leq \ldots \leq \lambda^n d(x_1,x_0)$  for  $1 \leq n$ . Thus, for m > n,

$$d(x_{m}, x_{n}) \leq d(x_{m}, x_{m-1}) + d(x_{m-1}, x_{m-2}) + \dots + d(x_{n+1}, x_{n})$$

$$\leq (\lambda^{m-1} + \lambda^{m-2} + \dots + \lambda^{n}) d(x_{1}, x_{0})$$

$$= \frac{\lambda^{n} (1 - \lambda^{m-n})}{1 - \lambda} d(x_{1}, x_{0})$$

$$\leq C \lambda^{n} d(x_{1}, x_{0})$$

This implies that the sequence  $x_1, x_2, \ldots$  is a Cauchy sequence. By completeness of X, it converges, say to an element  $\bar{x}$  of  $\mathcal{X}$ . But, since T is continuous,

$$T(\bar{x}) = T(\lim_{n \to \infty} x_n) = \lim_{n \to \infty} T(x_n) = \lim_{n \to \infty} x_{n+1} = \bar{x},$$

so,  $T(\bar{x}) = \bar{x}$ .

This proves the existence and the exponential convergence. QED.

The preceding theorem gives a useful sufficient condition for the existence of fixed points in a wide variety of situations. It is frequently useful to know when such fixed points depend continuously on parameters. This leads us to the next result.

**Definition.** Let  $\Lambda$  be a topological space (e.g. a metric space), and let  $\mathcal{X}$  be a complete metric space. A map T from  $\Lambda$  into the space of maps  $\mathcal{M}(X,X)$  is called a *continuous family of self-maps of*  $\mathcal{X}$  if the map  $\bar{T}(\lambda,x) = T(\lambda)(x)$  is continuous as a map from the product space  $\Lambda \times \mathcal{X}$  to  $\mathcal{X}$ . The map T is called a *uniform family of contractions* on  $\mathcal{X}$  if it is a continuous family of self-maps of  $\mathcal{X}$  and there is a constant  $0 < \alpha < 1$  such that

$$d(\bar{T}(\lambda, x), \bar{T}(\lambda, y)) \le \alpha d(x, y)$$

for all  $x, y \in \mathcal{X}, \lambda \in \Lambda$ .

Thus, the continuous family is a uniform family of contractions if and only if all the maps in the family have the same upper bound  $\alpha < 1$  for their Lipschitz constants.

Given the family T as above, we define the map  $T_{\lambda}: \mathcal{X} \to \mathcal{X}$  by

$$T_{\lambda}(x) = T(\lambda)(x) = \bar{T}(\lambda, x)$$

**Theorem.** If  $T: \Lambda \to \mathcal{M}(X,X)$  is a uniform family of contractions on  $\mathcal{X}$ , then each map  $T_{\lambda}$  has a unique fixed point  $x_{\lambda}$  which depends continuously on  $\lambda$ . That is, the map  $\lambda \to x_{\lambda}$  is a continuous map from  $\Lambda$  into  $\mathcal{X}$ .

**Proof.** Let  $g(\lambda)$  be the fixed point of the map  $T_{\lambda}$  which exists since the map  $T_{\lambda}$  is a contraction.

For  $\lambda_1, \lambda_2 \in \Lambda$ , we have

$$\begin{array}{lcl} d(g(\lambda_1),g(\lambda_2)) & = & d(T_{\lambda_1}g(\lambda_1),T_{\lambda_2}g(\lambda_2)) \\ & \leq & d(T_{\lambda_1}g(\lambda_1),T_{\lambda_1}g(\lambda_2)) + d(T_{\lambda_1}g(\lambda_2),T_{\lambda_2}g(\lambda_2)) \\ & \leq & \alpha d(g(\lambda_1),g(\lambda_2)) + d(T_{\lambda_1}g(\lambda_2),T_{\lambda_2}g(\lambda_2)) \end{array}$$

This implies that

$$d(g(\lambda_1), g(\lambda_2)) \le (1 - \alpha)^{-1} d(T_{\lambda_1} g(\lambda_2), T_{\lambda_2} g(\lambda_2))$$

Since the map  $\lambda \to T_{\lambda}g(\lambda_2)$  is continuous for fixed  $\lambda_2$ , we see that  $\lambda \to g(\lambda)$  is continuous. QED.

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There is another useful criterion for the existence of fixed points of transformations in Banach spaces.

Let X be a Banach space. Let  $x, y \in X$ . The line segment in X from x to y is the set of points  $\{(1-t)x+ty: 0 \le t \le 1\}$ . A subset F of X is called *convex* if for any two points  $x, y \in F$ , each point in the line segment from x to y is contained in F.

Examples:

- 1. Linear subspaces are convex.
- 2. open and closed balls are convex

The following are three remarkable theorems.

**Theorem.** (Brouwer Fixed Point Theorem). Every continuous map T of the closed unit ball in  $\mathbb{R}^n$  to itself has a fixed point.

**Theorem.**(Schauder Fixed Point Theorem). Every continuous self-map of a compact convex subset of a Banach space has a fixed point.

**Theorem.**(Schauder-Tychonov Fixed Point Theorem). Every continuous self-map of a compact convex subset of a locally convex linear topological space to itself has a fixed point.